

# STAT 221: STATISTICAL COMPUTING METHODS

Spring, 2004

Solution keys of ASSIGNMENT 1

Due on Mar. 3, 2004

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1.

- Based on the definition of Newton's method, it is not hard to show the given form.
- The right hand side of the iterative form has a minimum at  $x_{n-1} = c^{1/m}$  and the minimum is  $c^{1/m}$  where  $c > 0$ . Thus,  $x_n \geq c^{1/m}$  for all  $x_{n-1} > 0$ .
- Since  $x_{n-1} \geq c^{1/m}$ , we have

$$1 - \frac{1}{m} + \frac{c}{mx_{n-1}^m} \leq 1 - \frac{1}{m} + \frac{c}{mc^{m/m}} = 1,$$

which leads to  $x_n \leq x_{n-1}$ .

- Letting  $g(x_{n-1}) = x_n - x_{n-1}$ , we can show that  $g'(x_{n-1}) < 0$  whenever  $x_{n-1} \geq c^{1/m}$ , i.e.,  $x_n$  monotonely decrease to  $c^{1/m}$ , which is the minimum value.
- Based on the first result,  $x_1$  will be greater than  $c^{1/m}$  when  $0 < x_0 < c^{1/m}$ , but thereafter,  $x_n$  will monotonely decrease to  $c^{1/m}$  because of  $x_1 > c^{1/m}$ .

2.

- (a) In order to converge a positive solution of the equation,  $|f'(x)| < 1$  should be satisfied. After setting  $g(x) = 3x^2 - e^x$  at the first step, we know the first solution of this equation will be between 0 and 1 because of  $g(0) < 0$  and  $g(1) > 0$ , and the second solution between 3 and 4 because of  $g(3) > 0$  and  $g(4) < 0$ . In the vicinity of both roots, however, it is easy to confirm  $|f'(x_\infty)|$  is greater than 1.

Thus, we let  $f(x) = cg(x) + x$ , then try to find a value of  $c$  such that  $-2 < cg'(x) < 0$  is satisfied. First, since  $g'(x)$  is greater than 0 in the vicinity of the first solution, we have  $0 < g'(x) < -2/c$  where  $c$  is negative, which means  $c$  should be between  $-1/(3 \log 6 - 3)$  and 0 because  $g'(x)$  has an upper bound of  $(6 \log 6 - 6)$ . As long as  $c$  is set to a number somewhere in this interval, we guarantee that fixed-point iteration will converge to a positive (first) solution on an interval that satisfies  $g'(x) > 0$ . Finding the interval gives birth to another non-linear equation problem, but this can be done easily by using the bisection method. For instance, when we set  $c = -1/4$ , the solution to this equation is  $x^* = 0.9100076$  and the corresponding interval on which the fixed-point iteration converges is  $(0.2044814, 2.833148)$ .

Second,  $g'(x)$  is less than 0 in the vicinity of the second solution, and thus we have  $-2/c < g'(x) < 0$  where  $c$  is positive. Because  $g'(x)$  does not have a lower bound, the interval that converges to a positive (second) solution will hinge on the value of  $c$ . When we set  $c = 1/100$ , the solution to this equation is  $x^* = 3.733079$  and the corresponding interval on which the fixed-point iteration converges is  $(2.833148, 5.449743)$ .

- (b) For our first guess, we let  $f(x) = 2x - \cos x$  after setting  $g(x) = x - \cos x$ . However,  $|f'(x)| < 1$  cannot be satisfied for any value of  $x$ . Thus, we again let  $f(x) = cg(x) + x$ , then try to find  $c$  that satisfies the proposition. It is easy to see when  $c \in (-1, 0)$ ,  $|f'(x)| < 1$  is always satisfied for all  $x$  except odd multipliers of  $\pi$  plus  $\pi/2$ . The solution to this equation is  $x^* = 0.7390851$ .

### 3.

The likelihood function can be viewed as

$$\prod_{i=1}^n \left\{ (pf(t_i))^{z_i} (1 - pF(t_i))^{1-z_i} \right\},$$

then the loglikelihood is given by

$$\ell = \sum_{i=1}^n \left\{ z_i \log(pf(t_i)) + (1 - z_i) \log(1 - pF(t_i)) \right\}.$$

Thus, the first and second derivatives are given by

$$\begin{aligned} \frac{\partial \ell}{\partial p} &= \frac{\sum_{i=1}^n z_i}{p} - \sum_{i=1}^n \frac{(1 - z_i)F(t_i)}{1 - pF(t_i)} \\ \frac{\partial^2 \ell}{\partial p^2} &= -\frac{\sum_{i=1}^n z_i}{p^2} - \sum_{i=1}^n \frac{(1 - z_i)F(t_i)^2}{(1 - pF(t_i))^2}. \end{aligned}$$

Then we find a solution that satisfies  $\ell'(p) = 0$  by using Newton-Raphson and bisection as follows:

```
risk <- read.table("c:/Splus/Data/risk.dat",header=T)
z <- (risk[,2]-40)/15 # We standardize the data.

ell.f <- function(p){ sum(risk[,1])/p-sum((1-risk[,1])*pnorm(z)/(1-p*pnorm(z))) }
ell.s <- function(p){ -sum(risk[,1])/p^2-sum((1-risk[,1])*pnorm(z)^2/(1-p*pnorm(z))^2) }

### Bisection ###
a <- .4
b <- .6
ell.f(a)*ell.f(b) # Is this less than 0?
while(abs(a-b)>1.0e-8){
  c <- (a+b)/2
  if(ell.f(c)==0){
    print("optimal value!")
    break
  }
  else{
    if(ell.f(a)*ell.f(c)<0) b <- c
    else a <- c
  }
}
c # 0.5058496

### Newton-Raphson ###
x <- .4
while(abs(ell.f(x))>1.0e-8) x <- x - ell.f(x)/ell.s(x)
x # 0.5058496

sqrt(-1/ell.s(x)) # 0.0704326 which is the standard error of p.hat.
```

4.

For any non-negative integers  $n$  and  $m$  where  $n > m$ ,

$$\|B_n - B_m\| = \left\| \sum_{k=m+1}^n \frac{A^k}{k!} \right\| \leq \sum_{k=m+1}^n \frac{\|A^k\|}{k!} \leq \sum_{k=m+1}^n \frac{\|A\|^k}{k!} < \sum_{k=m+1}^{\infty} \frac{\|A\|^k}{k!}$$

and the right-hand side will converge to 0 as  $m \rightarrow \infty$ . Thus  $B_n$  is a Cauchy sequence, so it will converge in the reals.

In particular, if we assume  $A$  is a  $p \times p$  symmetric matrix, then by an eigen decomposition  $A$  can be decomposed into  $QDQ^{-1}$  where  $D$  is a diagonal matrix whose entries are eigenvalues and  $Q$  is a matrix of corresponding eigenvectors. Thus, the given series can be rewritten as

$$B_n = \sum_{k=0}^n \frac{A^k}{k!} = Q \left( \sum_{k=0}^n \frac{D^k}{k!} \right) Q^{-1} = Q \begin{vmatrix} \sum_k \frac{d_1^k}{k!} & 0 & \dots & 0 \\ 0 & \sum_k \frac{d_2^k}{k!} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sum_k \frac{d_p^k}{k!} \end{vmatrix} Q^{-1},$$

and as  $n \rightarrow \infty$  this will converge to

$$Q \begin{vmatrix} e^{d_1} & 0 & \dots & 0 \\ 0 & e^{d_2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & e^{d_p} \end{vmatrix} Q^{-1} \equiv Qe^DQ^{-1}.$$

5.

- $1 = \|I\| = \|AA^{-1}\| \leq \|A\| \cdot \|A^{-1}\| = \text{cond}(A)$ .
- $\text{cond}(A^{-1}) = \|A^{-1}\| \cdot \|A\| = \|A\| \cdot \|A^{-1}\| = \text{cond}(A)$ .
- $\text{cond}(cA) = |c| \cdot \|A\| \cdot |c^{-1}| \cdot \|A^{-1}\| = \|A\| \cdot \|A^{-1}\| = \text{cond}(A)$ .
- $\text{cond}_2(U) = \|U\|_2 \cdot \|U^{-1}\|_2 = \sqrt{\rho(U^T U)} \sqrt{\rho(U^{-T} U^{-1})} = \sqrt{\rho(U^T U)} \sqrt{\rho(UU^T)} = 1$ .
- $\text{cond}_2(AU) = \|AU\|_2 \cdot \|U^{-1}A^{-1}\|_2 = \|U^T A^T\|_2 \cdot \|U^{-1}A^{-1}\|_2 = \|A^T\|_2 \cdot \|A^{-1}\|_2 = \text{cond}_2(A)$ .
- $\text{cond}_2(UA) = \|UA\|_2 \cdot \|A^{-1}U^{-1}\|_2 = \|UA\|_2 \cdot \|U^{-T}A^{-T}\|_2 = \|A\|_2 \cdot \|A^{-T}\|_2 = \text{cond}_2(A)$ .